Script.TRACER.CHEVROLET.TAHOE.POS4.1GNSK8ED_PR.v1.20.1.0_MG

CHEVROLET TAHOE 2023 CAN Script



The compatibility if this script can only be guaranteed for:

- 1. Chevrolet Tahoe 2023 model
- 2. Vehicles with a VIN Number that starts with: **1GNSK8ED_PR**

This script can be used with the following devices:

1. Tracer



Version History

| Reference | Version | Changes |
|-----------------|-----------|--|
| <u>SCR-2673</u> | v1.20.1.0 | This script supports the standard system Parameters: Engine Speed, Vehicle Speed, Odometer, Vehicle Range, Fuel, Fuel Level, Total Engine Hours, Accelerator Pedal Position, Brake Pedal Switch, Driver Seat Belt, Passenger Seat Belt, Gearbox Drive, Gearbox Reverse, Gearbox Neutral, Gearbox Park, Gearbox Mode, Park Brake, Driver Door 1, Driver Door 2, Passenger Door 1, Passenger Door 2, Side Lamp, Indicator Left, Indicator Right, Head Light State, Cruise Control State, Passenger Weight Sensor. The script should be compatible with vehicles with a VIN starting with: 1GNSK8ED_PR *Based on GM script, <u>Script,CAN,GM,GLOBAL-B-</u> POWERTRAIN,v1.19.3.2 MG BETA |
| <u>SCR-2673</u> | v1.20.1.0 | Tracer version. |

Supported Parameters

| ACRONYM | PARAMETER NAME | PARAMETER DESCRIPTION | Return values/states (if applicable) |
|---------|---------------------|--|---|
| CAN_N | System.Scratch40C | Engine RPM | |
| CAN_V | System.Scratch40D | Vehicle Speed | |
| CANFE | System.CAN.FuelRate | Fuel Rate | |
| FMODO | System.FM.CAN.FMODO | FM CAN: Odometer (introduced 27/11/2019) | |
| FMSFL | FMS.FMSFL | FMS Fuel level | |
| FMRNG | System.FM.CAN.FMRNG | FM CAN: Vehicle range remaining | |
| FMTEH | FMS.FMTEH | FMS DM Total engine hours | |
| THRPA | System.FM.CAN.THRPA | FM CAN: Throttle Pedal Angle | |
| BRKPS | System.FM.CAN.BRKPS | FM CAN: Brake Pedal State | 0 = NOT PRESENT 1 = ENGAGED 2 = DISENGAGED |
| GBDRM | System.FM.CAN.GBDRM | FM CAN: Gear Box Drive Mode | 0 = NOT PRESENT 1 = PARK 2 = REVERSE 3 = NEUTRAL 4 = DRIVE 5 = LOW GEAR 6 = NOT DEFINED |
| GBDM1 | System.FM.CAN.GBDM1 | FM CAN: Gear Box Mode Park | 0 = DISENGAGED / NOT PRESENT 1 = ENGAGED |
| GBDM2 | System.FM.CAN.GBDM2 | FM CAN: Gear Box Mode Reverse | 0 = DISENGAGED / NOT PRESENT 2 = ENGAGED |
| GBDM3 | System.FM.CAN.GBDM3 | FM CAN: Gear Box Mode Neutral | 0 = DISENGAGED / NOT PRESENT 3 = ENGAGED |
| GBDM4 | System.FM.CAN.GBDM4 | FM CAN: Gear Box Mode Drive | 0 = DISENGAGED / NOT PRESENT 4 = ENGAGED |
| GBDM5 | System.FM.CAN.GBDM5 | FM CAN: Gear Box Mode Low Gear | 0 = DISENGAGED / NOT PRESENT 5 = ENGAGED |
| DD01S | System.FM.CAN.DD01S | FM CAN: Driver Door 1 | 0 = NOT PRESENT 1 = OPEN 2 = CLOSED |

| DD02S | System.FM.CAN.DD02S | FM CAN: Driver Door 2 | 0 = NOT PRESENT 1 = OPEN 2 = CLOSED |
|--------|---------------------|---------------------------------------|--|
| LTSSI | System.FM.CAN.LTSSI | FM CAN: Left Turn Indicator | 0 = NOT PRESENT 1 = ON 2 = OFF |
| RTSSI | System.FM.CAN.RTSSI | FM CAN: Right Turn Indicator | 0 = NOT PRESENT 1 = ON 2 = OFF |
| PBRKS | System.FM.CAN.PBRKS | FM CAN: Park Brake State | 0 = NOT PRESENT 1 = DISENGAGED 2 = ENGAGED |
| PDO\$1 | System.FM.CAN.PDOS1 | FM CAN: Passenger Door 1 | 0 = NOT PRESENT 1 = OPEN 2 = CLOSED |
| PDOS2 | System.FM.CAN.PDOS2 | FM CAN: Passenger Door 2 | 0 = NOT PRESENT 1 = OPEN 2 = CLOSED |
| SBLTS | System.FM.CAN.SBLTS | FM CAN: Seat Belt State | 0 = NOT PRESENT 1 = PLUGGED IN 2 = UNPLUGGED |
| PSBLT | System.FM.CAN.PBELT | FM CAN: Passenger Seat Belt Status | 0 = NOT PRESENT 1 = PLUGGED IN 2 = UNPLUGGED |
| SDLMP | System.FM.CAN.SDLMP | FM CAN: Side lamp status | 0 = NOT PRESENT 1 = ON 2 = OFF |
| FCCST | System.FM.CAN.FCCST | FM CAN: Cruise Control State | -1 = NOT PRESENT 0 = OFF 1 = STANDBY 2 = ENABLED 3 = REGULATING 6 = NOT DEFINED |
| PWSNS | System.FM.CAN.PWSNS | FM CAN: Passenger Weight Sensor | 0 = NOT PRESENT 1 = ON 2 = Off |



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Installation Notes

- 1. The script is ONLY compatible with TRACERS
- 2. The CAN jumpers must be in a position to ONLY allow **read** actions on the CAN bus (Passive Mode)
- 3. The script supports 11-bit CAN headers.
- 4. The script only supports a CAN bus with a speed of 500 kb/s
- 5. Device Drivers: <u>BAS 1.70k E15.08.27.xx</u> or later sets are supported

Wiring and Installation Instructions

| CAN bus location | 4) Behind Instrument Cluster | |
|------------------------|---|--|
| Wire colours & details | & details CAN HIGH = BLUE & WHITE & CAN LOW = BLUE & YELLOW | |
| Can bus speed | CAN_500_kbps | |